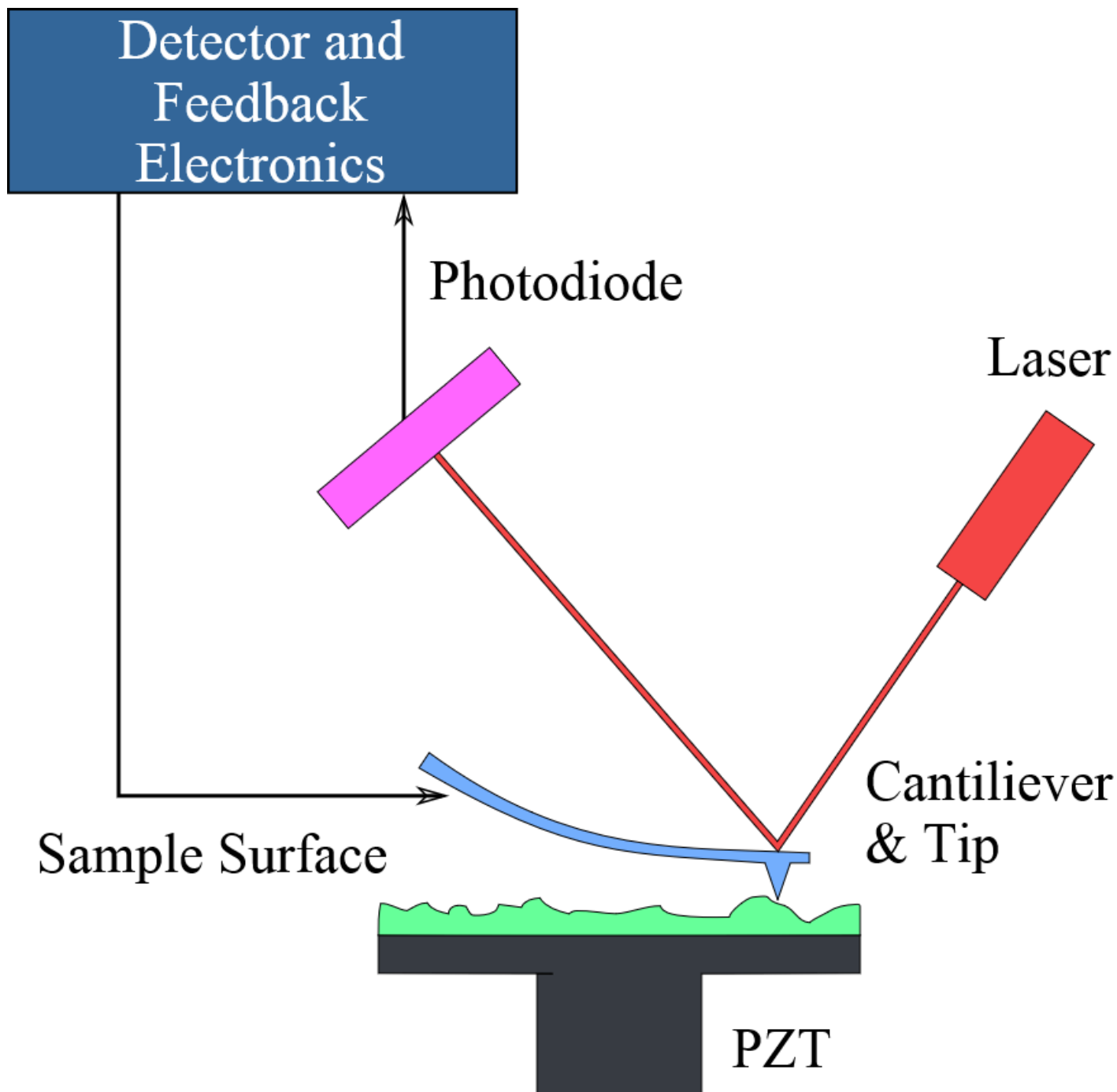
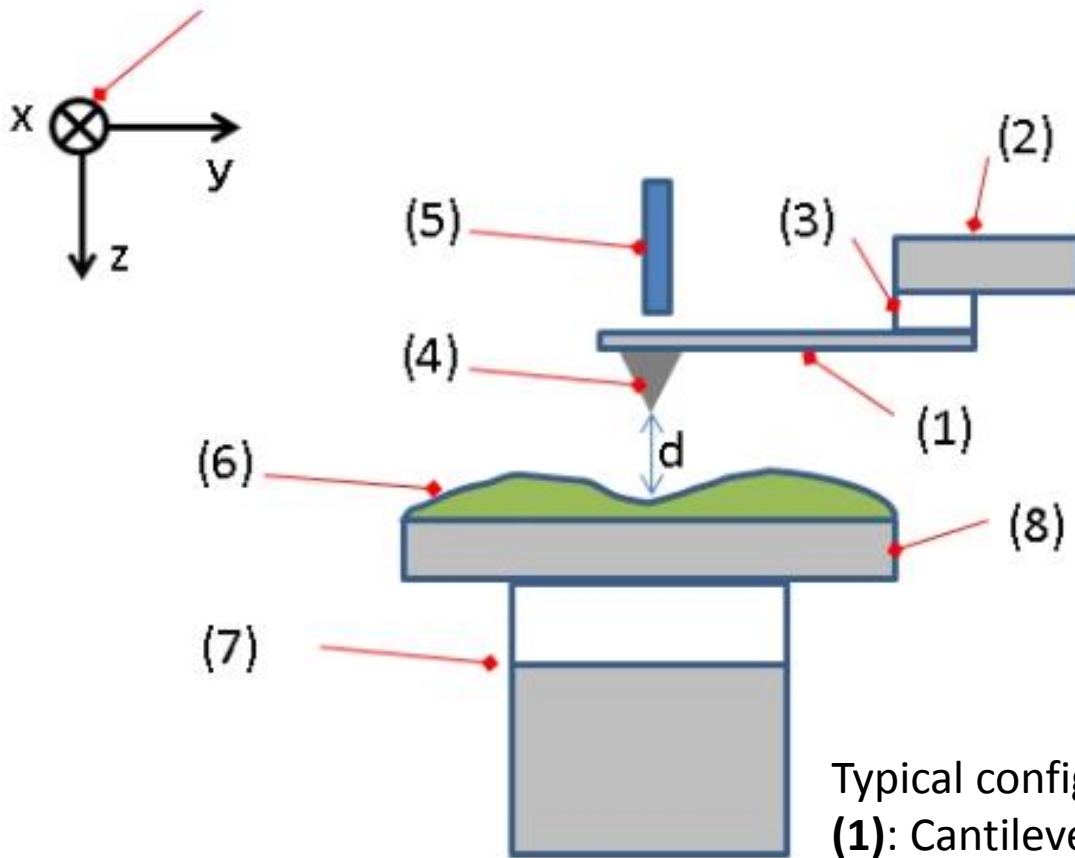


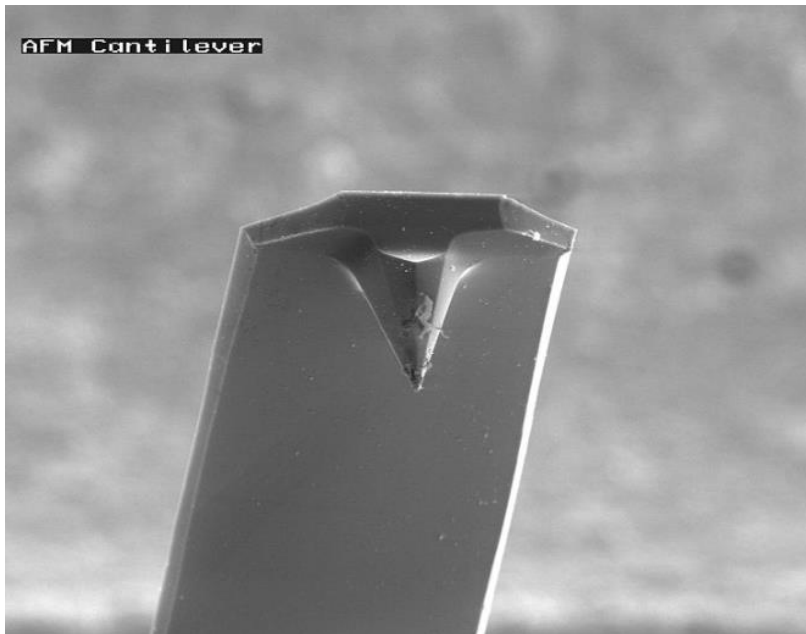
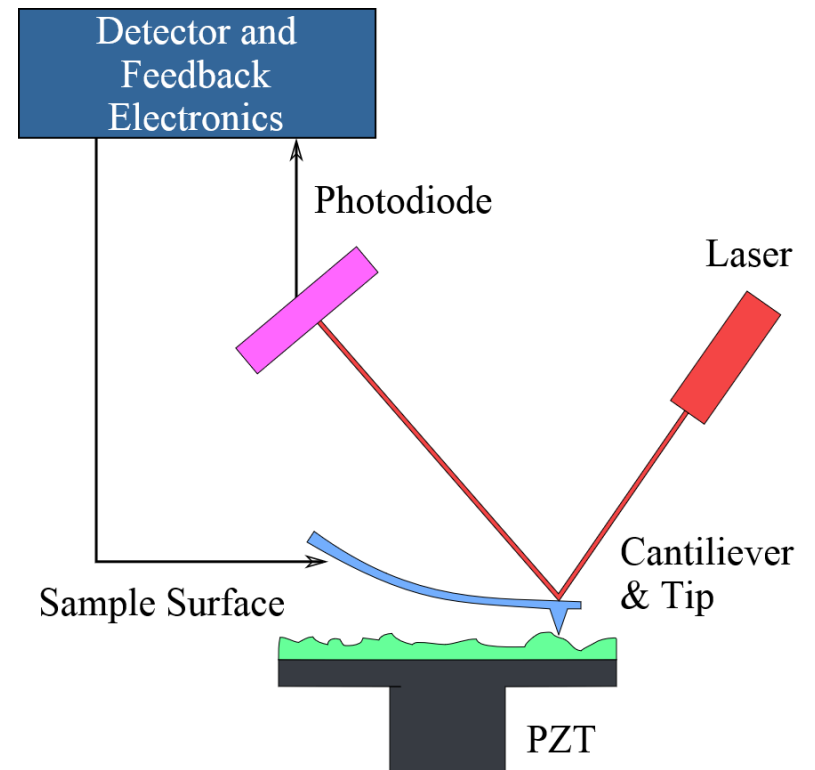
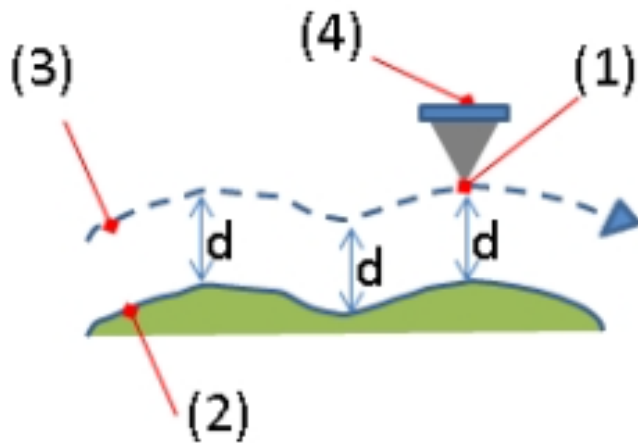
# **AFM ATOMIC FORCE MICROSCOPY**





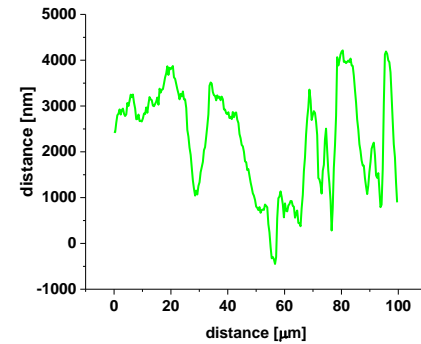
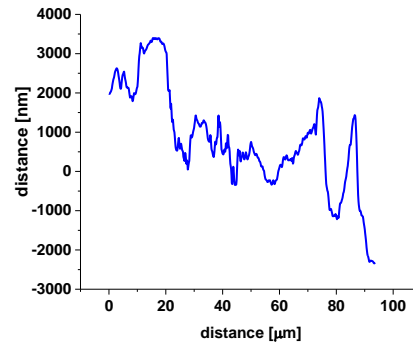
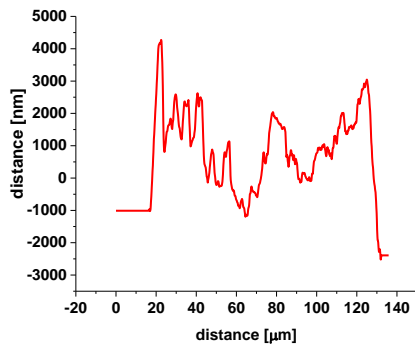
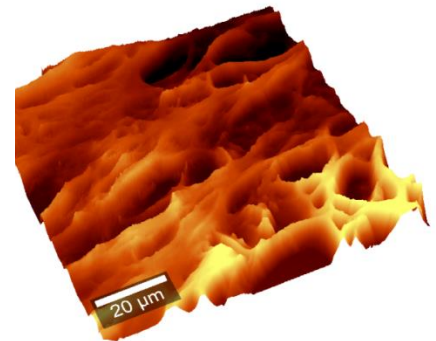
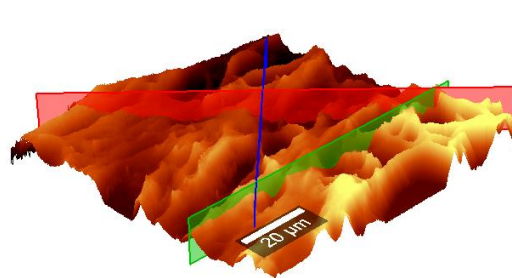
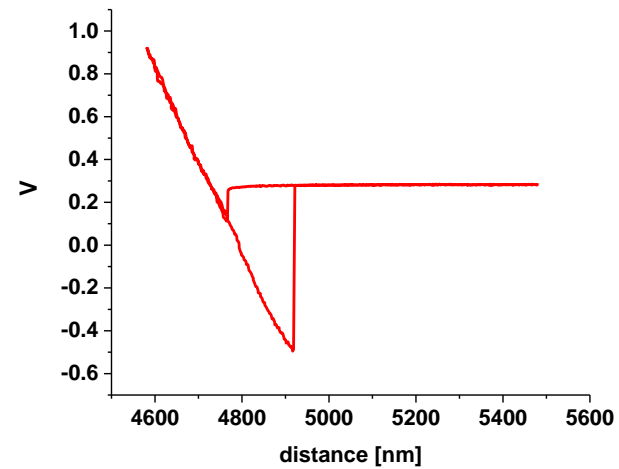
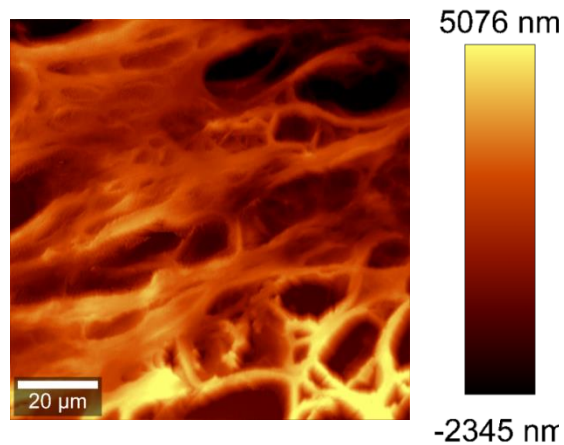
Typical configuration of an AFM.

**(1):** Cantilever, **(2):** Support for cantilever, **(3):** Piezoelectric element(to oscillate cantilever at its eigen frequency.), **(4):** Tip (Fixed to open end of a cantilever, acts as the probe), **(5):** Detector of deflection and motion of the cantilever, **(6):** Sample to be measured by AFM, **(7):** xyz drive, (moves sample (6) and stage (8) in x, y, and z directions with respect to a tip apex (4)), and **(8):** Stage

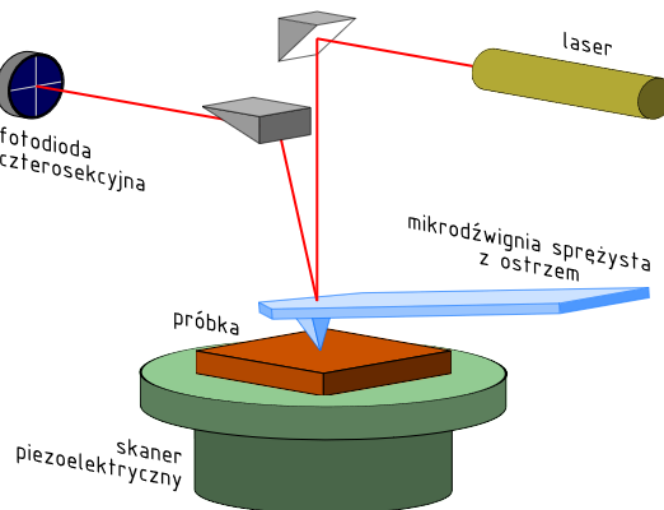
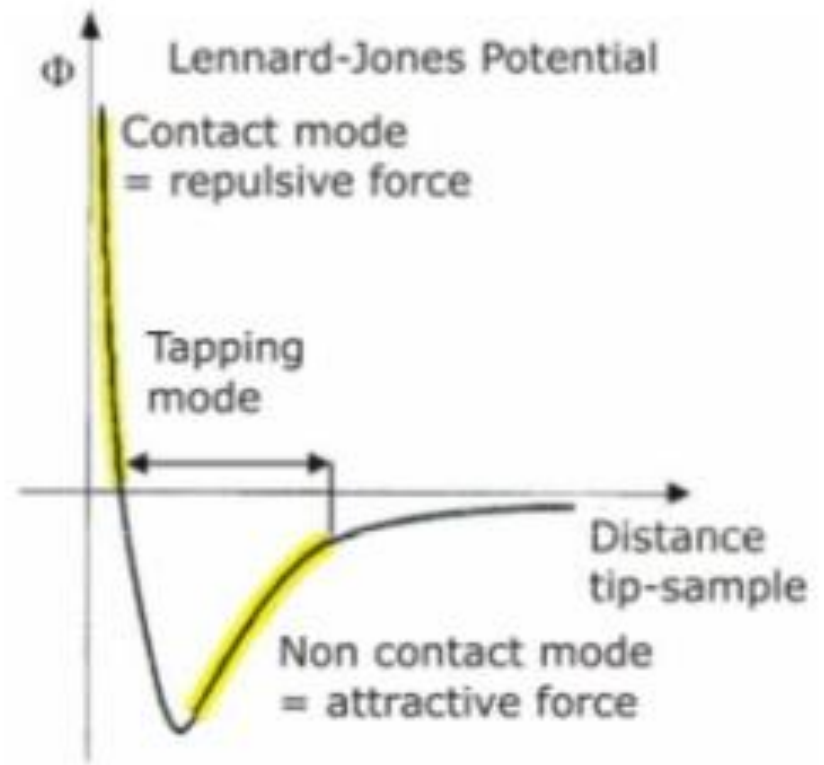


# Abilities:

force measurement  
imaging  
and manipulation



- Imaging mode
  - contact mode
  - non contact mode
  - intermittent / tapping mode
- Force-distance mode
  - force spectroscopy
  - combined imaging & force spectroscopy



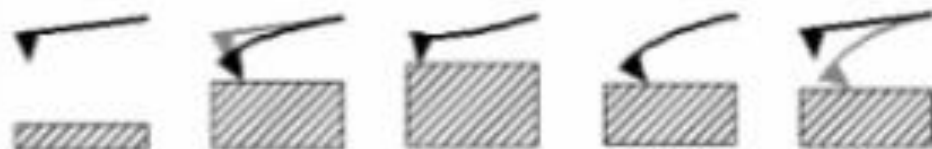
- Contact mode:
  - tip in continuous contact with sample
  - preferably used for hard samples
  - imaging in air and liquid
  - high resolution

detect: deflection



- Force spectroscopy mode:
  - consecutive cycles of tip approach and retract
  - interaction forces between tip and sample are recorded

$$F = - k_{\text{spring}} \cdot \Delta x$$



- Intermittent/tapping mode:
  - oscillating cantilever, tip touching surface gently and frequently
  - often used for biological samples
  - imaging in air and liquid
  - good resolution

Intermittent contact



- Non contact mode:
  - oscillating cantilever, tip not in contact with sample
  - used for soft samples
  - imaging in vacuum
  - distance range 50Å - 150Å

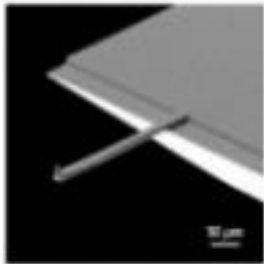
Non-contact mode



detect: amplitude  
phase  
deflection

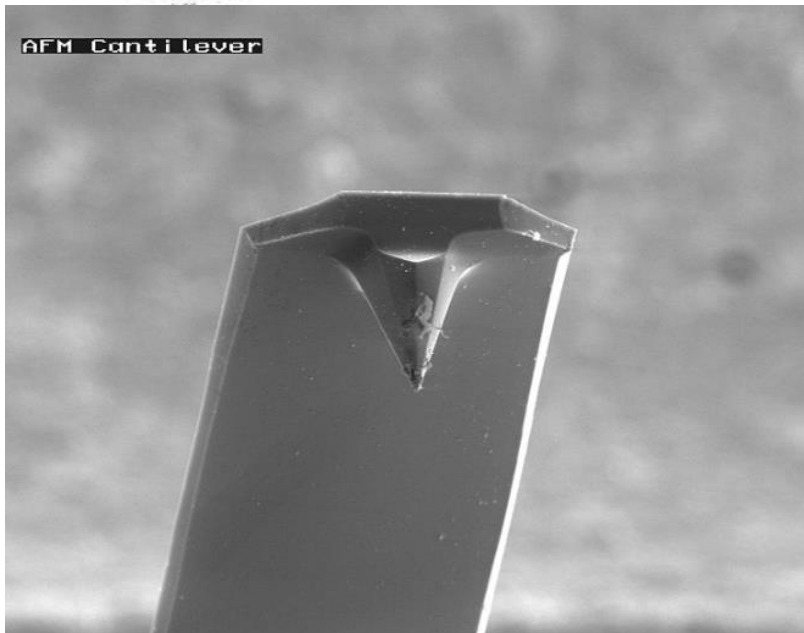
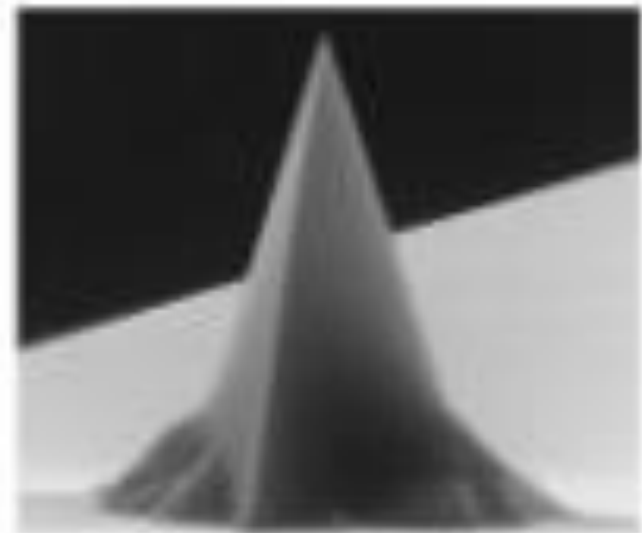


silicon nitride  
cantilevers

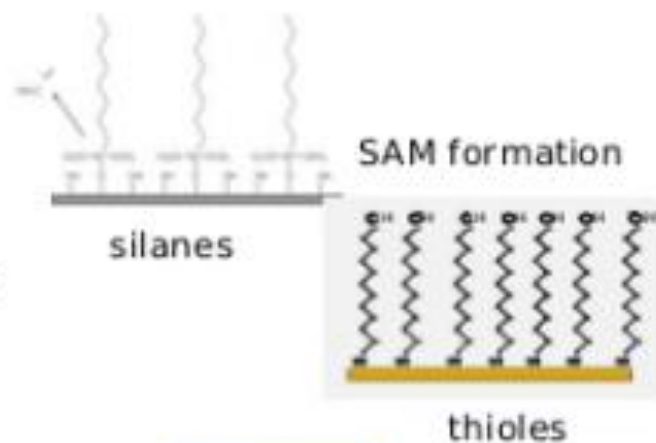


silicon

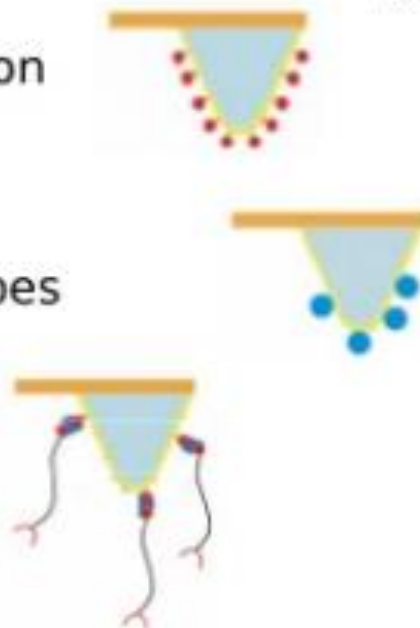
Typical cantilevers:  
 $1\mu\text{m}$  thick,  $100\text{s }\mu\text{m}$  long  
 $k_{\text{spring}} \sim 0.01 \dots 20\text{N/m}$   
 $f_{\text{res}} \sim 4 \dots 400\text{kHz}$   
 $r_{\text{tip}} \sim 1 \dots 20\text{nm}$   
 reflective backside coating:  
 - better signal



- Surface modification  
self assembling monolayers (SAM)
  - silanes on glass- and Si-surfaces
  - thioles on Au-surfaces



- Tip modification
  - Adsorption of molecules from solution  
e.g. proteins
  - Decrease AFM tip radius with  
attachment of molecules or nanotubes
  - Attachment of linker molecules  
e.g. PEG linker for antibodies,  
crosslinker for SH-, NH-groups

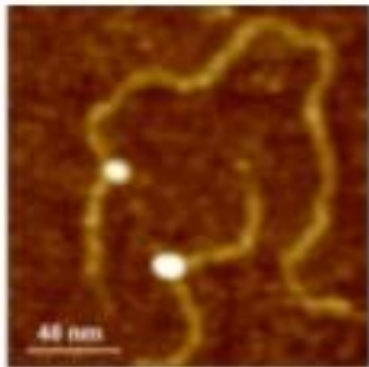


## Biomolecular structure

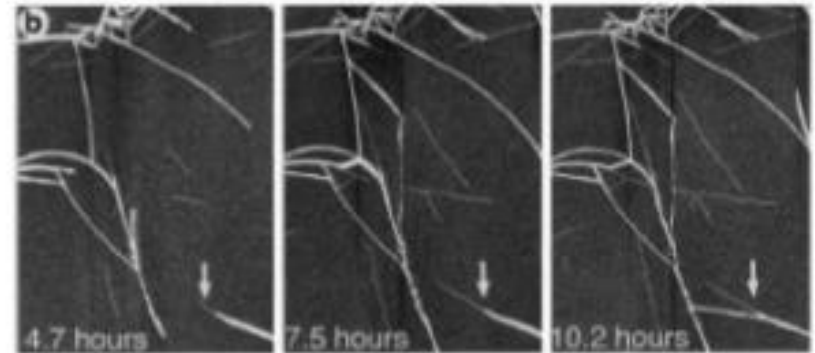
Imaging DNA-protein complexes on aminoterminated mica



DNA plasmids

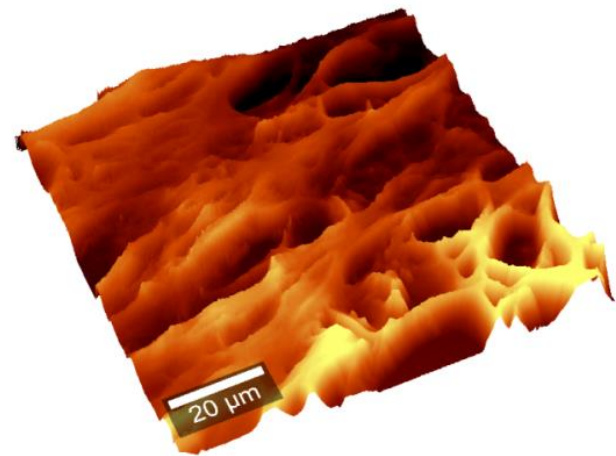


$\lambda$ -DNA restriction enzyme complex (Hae III restriction endonuclease induces bending at GGCC)

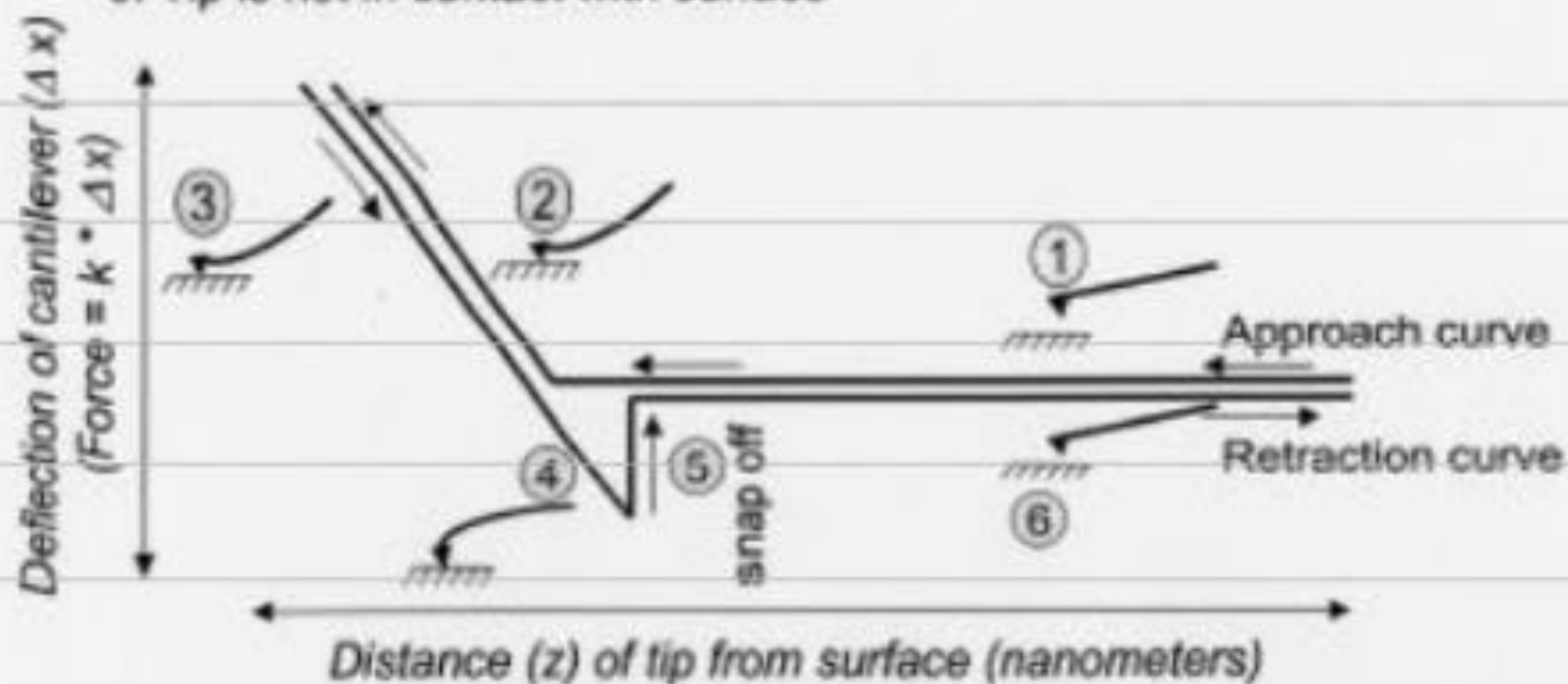


Time-lapse AFM for imaging growth of amyloid fibrils (synthetic human amylin)

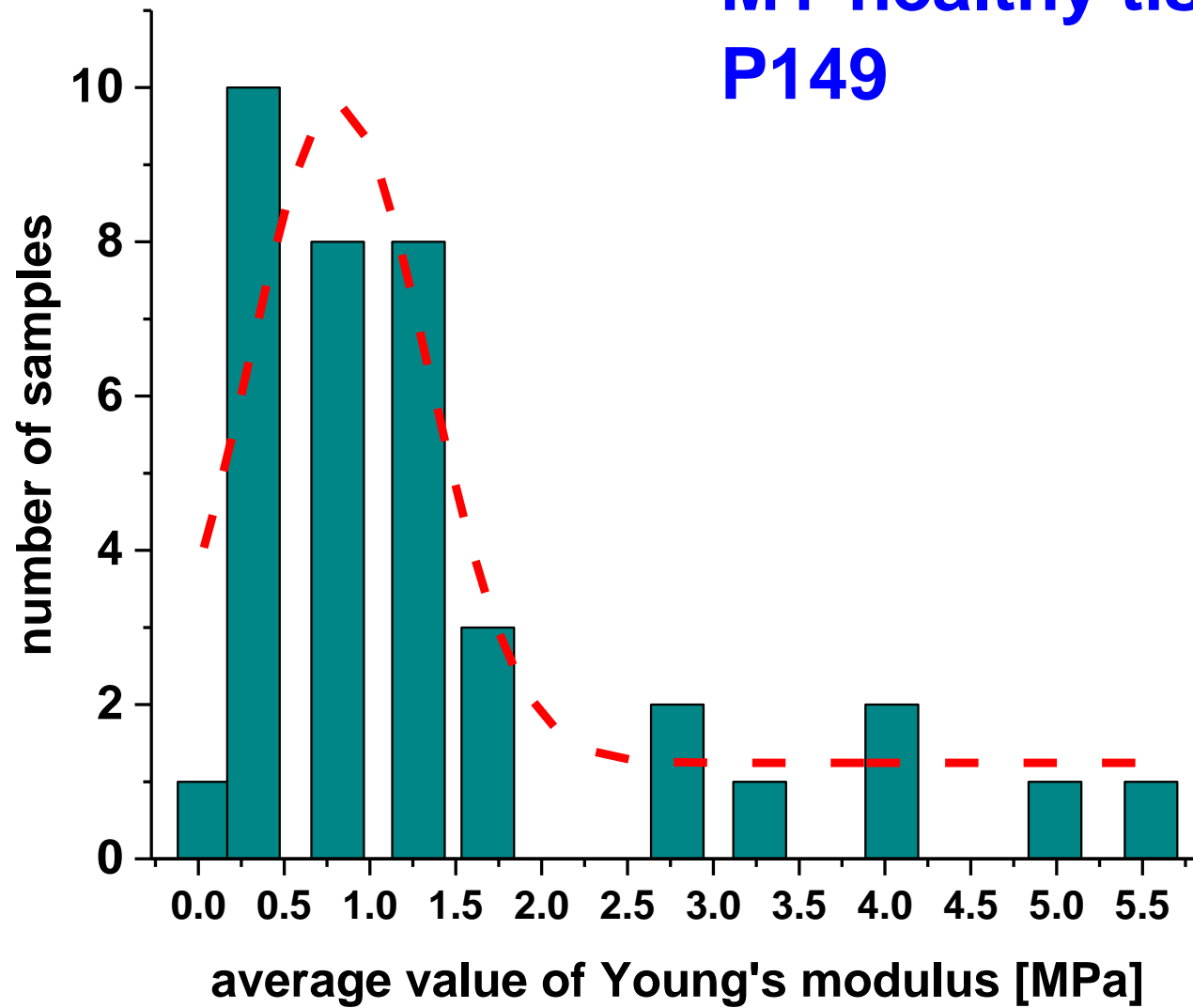
Goldsbury et al., J. Mol. Biol. 1999



1. AFM tip is not in contact with surface
2. Tip is being pushed into the surface, bending the cantilever
3. Tip is being withdrawn from the surface
4. Tip adheres to sample/surface
5. Tip "snaps off" from surface
6. Tip is not in contact with surface

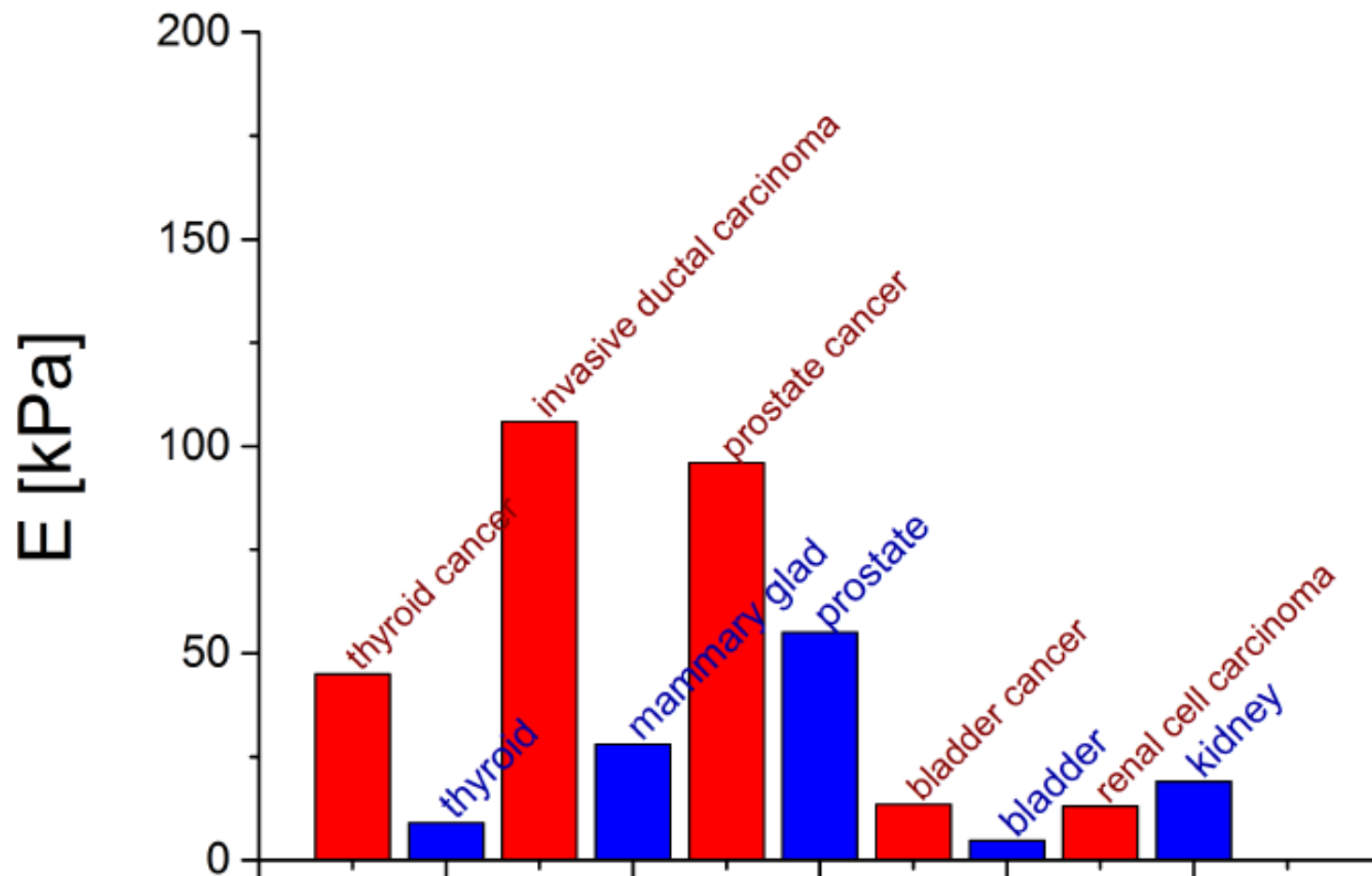


# MY healthy tissue P149

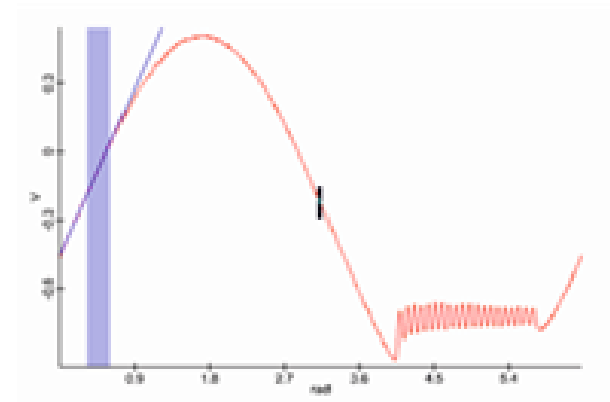
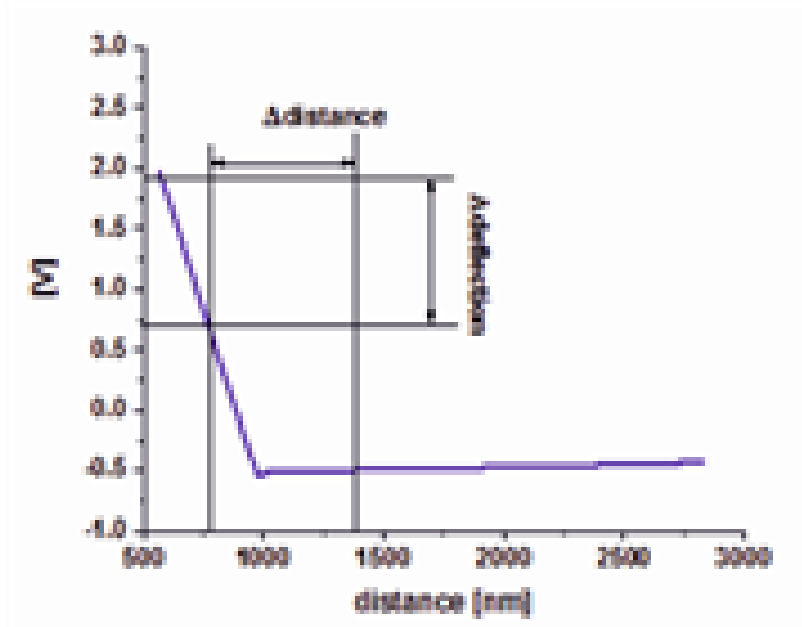


*Lee et al., Yonsei Med. J. (2011)*

*Krouskop et al. Ultrasonic Imaging, (1998)*



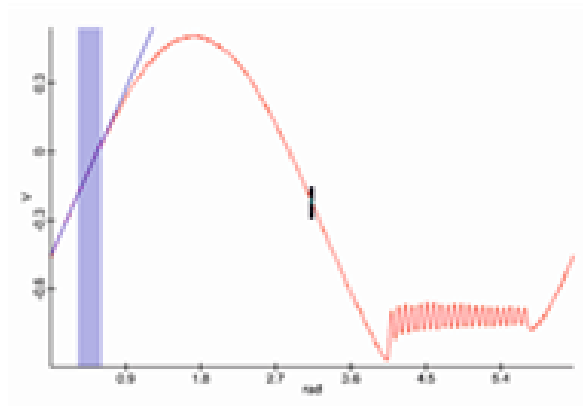
**NIŻSZY MODUŁ YOUNGA DLA TKANEK PRAWIDŁOWYCH**



$$Adhesion [nN] = k [N/m] * S [nm/V] * V_{adhesion} [V]$$

$$Sensitivity \left[ \frac{nm}{V} \right] = \frac{1}{slope}$$

$$Slope \left[ \frac{V}{nm} \right] = \Delta deflection / \Delta distance$$



$$M \text{ [nm]} = U * S * A$$

A – voltage applied to the cantilever

S – sensitivity of the detector

U – modulation factor

Penetration depth  $\Delta Z$  is calculated using the formula:

$$\Delta Z \text{ [nm]} = M * [1 - \cos(\Delta \text{rad})] - a_1 * (\Delta \text{rad}) * S$$

$$\text{Stiffness} \left[ \frac{N}{m} \right] = \frac{a_1 * (\Delta \text{rad}) * k * S}{\Delta Z}$$

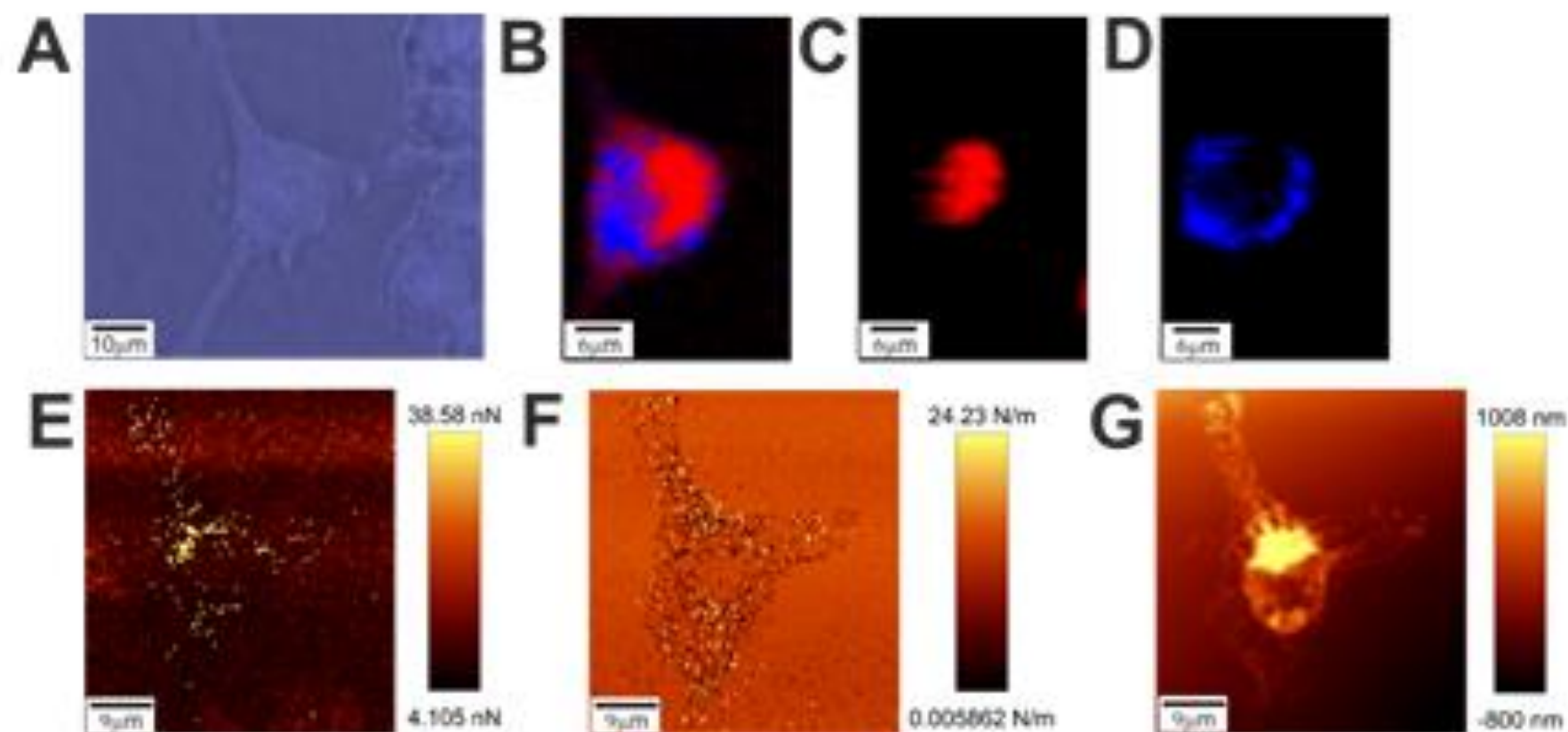


Fig 4. Microscopy image (A), Raman image (red-proteins, blue-lipids) (B), fluorescence images of Hoechst 33342 (C) and Oil Red O (D) of a living U-87 MG cell, adhesion image (E), stiffness image (F) and topography image (G) of air-dried cell.